

2009

The symmetric minimal rank solution of the matrix equation $AX=B$ and the optimal approximation

Qing-feng Xiao
qfxiao@hnu.cn

Xi-yan Hu

Lei Zhang

Follow this and additional works at: <http://repository.uwyo.edu/ela>

Recommended Citation

Xiao, Qing-feng; Hu, Xi-yan; and Zhang, Lei. (2009), "The symmetric minimal rank solution of the matrix equation $AX=B$ and the optimal approximation", *Electronic Journal of Linear Algebra*, Volume 18.
DOI: <https://doi.org/10.13001/1081-3810.1311>

This Article is brought to you for free and open access by Wyoming Scholars Repository. It has been accepted for inclusion in Electronic Journal of Linear Algebra by an authorized editor of Wyoming Scholars Repository. For more information, please contact scholcom@uwyo.edu.

THE SYMMETRIC MINIMAL RANK SOLUTION OF THE MATRIX EQUATION $AX = B$ AND THE OPTIMAL APPROXIMATION*

QING-FENG XIAO[†], XI-YAN HU[†], AND LEI ZHANG[†]

Abstract. By applying the matrix rank method, the set of symmetric matrix solutions with prescribed rank to the matrix equation $AX = B$ is found. An expression is provided for the optimal approximation to the set of the minimal rank solutions.

Key words. Symmetric matrix, Matrix equation, Maximal rank, Minimal rank, Fixed rank solutions, Optimal approximate solution.

AMS subject classifications. 65F15, 65F20.

1. Introduction. We first introduce some notation to be used. Let $C^{n \times m}$ denote the set of all $n \times m$ complex matrices; $R^{n \times m}$ denote the set of all $n \times m$ real matrices; $SR^{n \times n}$ and $ASR^{n \times n}$ be the sets of all $n \times n$ real symmetric and antisymmetric matrices respectively; $OR^{n \times n}$ be the sets of all $n \times n$ orthogonal matrices. The symbols A^T , A^+ , A^- , $R(A)$, $N(A)$ and $r(A)$ stand, respectively, for the transpose, Moore-Penrose generalized inverse, any generalized inverse, range (column space), null space and rank of $A \in R^{n \times m}$. The symbols E_A and F_A stand for the two projectors $E_A = I - AA^-$ and $F_A = I - A^-A$ induced by A . The matrices I and 0 denote, respectively, the identity and zero matrices of sizes implied by the context. We use $\langle A, B \rangle = \text{trace}(B^T A)$ to define the inner product of matrices A and B in $R^{n \times m}$. Then $R^{n \times m}$ is an inner product Hilbert space. The norm of a matrix generated by the inner product is the Frobenius norm $\|\cdot\|$, that is, $\|A\| = \sqrt{\langle A, A \rangle} = (\text{trace}(A^T A))^{\frac{1}{2}}$.

Ranks of solutions of linear matrix equations have been considered previously by several authors. For example, Mitra [1] considered solutions with fixed ranks for the matrix equations $AX = B$ and $AXB = C$; Mitra [2] gave common solutions of minimal rank of the pair of matrix equations $AX = C, XB = D$; Uhlig [3] gave the maximal and minimal ranks of solutions of the equation $AX = B$; Mitra [4] examined common solutions of minimal rank of the pair of matrix equations $A_1 X_1 B_1 = C_1$ and $A_2 X_2 B_2 = C_2$. Recently, by applying the matrix rank method, Tian [5] obtained

*Received by the editors February 25, 2009. Accepted for publication May 9, 2009. Handling Editor: Ravindra B. Bapat.

[†]College of Mathematics and Econometrics, Hunan University, Changsha 410082, P.R. of China (qfxiao@hnu.cn). Research supported by National Natural Science Foundation of China (under Grant 10571047) and the Doctorate Foundation of the Ministry of Education of China (under Grant 20060532014).

the minimal rank among solutions to the matrix equation $A = BX + YC$. Theoretically speaking, the general solution of a linear matrix equation can be written as linear matrix expressions involving variant matrices. Hence the maximal and minimal ranks among the solutions of a linear matrix equation can be determined through the corresponding linear matrix expressions.

Motivated by the work in [1,3], in this paper, we derive the minimal and maximal rank among symmetric solutions to the matrix equation $AX = B$ and obtain the symmetric matrix solution with prescribed rank. In addition, in corresponding minimal rank solution set of the equation, an explicit expression for the nearest matrix to a given matrix in the Frobenius norm is provided.

The problems studied in this paper are described below.

Problem I. Given $X \in R^{n \times m}$, $B \in R^{n \times m}$, and a positive integer s , find $A \in SR^{n \times n}$ such that $AX = B$, and $r(A) = s$. Moreover, when the solution set $S_1 = \{A \in SR^{n \times n} | AX = B\}$ is nonempty, find

$$\tilde{m} = \min_{A \in S_1} r(A), \tilde{M} = \max_{A \in S_1} r(A),$$

and determine the symmetric minimal rank solution in S_1 , that is $S_{\tilde{m}} = \{A | r(A) = \tilde{m}, A \in S_1\}$.

Problem II. Given $A^* \in R^{n \times n}$, find $\tilde{A} \in S_{\tilde{m}}$ such that

$$\|A^* - \tilde{A}\| = \min_{A \in S_{\tilde{m}}} \|A^* - A\|.$$

The paper is organized as follows. First, in Section 2, we will introduce several lemmas which will be used in the later sections. Then, in Section 3, applying the matrix rank method, we will discuss the rank of the general symmetric solution to the matrix equation $AX = B$, where X, B are given matrices in $R^{n \times m}$. Based on this, the symmetric solution set with prescribed ranks to the matrix equation $AX = B$ will be presented. Lastly, in Section 4, an expression for the optimal approximation to the set of the minimal rank solution $S_{\tilde{m}}$ will be provided.

2. Some lemmas. The following lemmas are essential for deriving the solution to Problem 1.

LEMMA 2.1. [6] *Let A, B, C , and D be $m \times n, m \times k, l \times n, l \times k$ matrices, respectively. Then*

$$(2.1) \quad r \begin{pmatrix} A \\ C \end{pmatrix} = r(A) + r(C(I - A^-A)),$$

$$(2.2) \quad r \begin{pmatrix} A & B \\ C & D \end{pmatrix} = r \begin{pmatrix} A \\ C \end{pmatrix} + r \begin{pmatrix} A & B \end{pmatrix} - r(A) + r[E_G(D - CA^-B)F_H],$$

where $G = CF_A$ and $H = E_AB$.

LEMMA 2.2. [7] Assume $K \in R^{m \times n}$, $Y \in R^{p \times m}$ are full-column rank matrices, $Z \in R^{n \times q}$ is full-row rank matrix. Then

$$r(K) = r(YK) = r(KZ) = r(YKZ).$$

LEMMA 2.3. [7] Suppose that $L \in R^{n \times n}$ satisfies $L^2 = L$. Then

$$r(L) = \text{trace}(L).$$

LEMMA 2.4. [7]

$$r(MM^+) = r(M).$$

LEMMA 2.5. [7] Given $S \in R^{m \times n}$, and $J \in R^{k \times m}$, $W \in R^{l \times n}$ satisfying $J^T J = I_m$, $W^T W = I_n$, then

$$(JSW^T)^+ = WS^+J^T.$$

LEMMA 2.6 (8). Given $X, B \in R^{n \times m}$, let the singular value decompositions of X be

$$(2.3) \quad X = U \begin{pmatrix} \Sigma & 0 \\ 0 & 0 \end{pmatrix} V^T = U_1 \Sigma V_1^T,$$

where $U = (U_1, U_2) \in OR^{n \times n}$, $U_1 \in R^{n \times k}$, $V = (V_1, V_2) \in OR^{m \times m}$, $V_1 \in R^{m \times k}$, $k = r(X)$, $\Sigma = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_k)$, $\sigma_1 \geq \dots \geq \sigma_k > 0$. Then $AX = B$ is solvable in $SR^{n \times n}$ if and only if

$$(2.4) \quad BV_2 = 0, X^T B = B^T X,$$

and its general solution can be expressed as

$$A = U \begin{pmatrix} U_1^T B V_1 \Sigma^{-1} & \Sigma^{-1} V_1^T B^T U_2 \\ U_2^T B V_1 \Sigma^{-1} & A_{22} \end{pmatrix} U^T, \quad \forall A_{22} \in SR^{(n-k) \times (n-k)}.$$

3. General expression of the solutions to Problem I. Now consider Problem 1 and suppose that (2.4) holds. Then the general symmetric solution of the equation $AX = B$ can be expressed as

$$(3.1) \quad A = U \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} U^T$$

where

$$A_{11} = U_1^T B V_1 \Sigma^{-1} \in SR^{k \times k}, \quad A_{12} = \Sigma^{-1} V_1^T B^T U_2 \in R^{k \times (n-k)}$$

and

$$A_{21} = U_2^T B V_1 \Sigma^{-1} \in R^{(n-k) \times k}$$

satisfy

$$A_{11} = A_{11}^T, \quad A_{21} = A_{12}^T, \quad A_{22} = A_{22}^T.$$

By Lemma 2.2 and the orthogonality of U , we obtain

$$(3.2) \quad r(A) = r \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}.$$

Let

$$r \begin{pmatrix} A_{11} \\ A_{21} \end{pmatrix} + r \begin{pmatrix} A_{11} & A_{12} \end{pmatrix} - r(A_{11}) = t.$$

Applying (2.2) to A in (3.2), we have

$$r(A) = t + r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}],$$

where $G_1 = A_{21}(I - A_{11}^-A_{11})$, $H_1 = (I - A_{11}A_{11}^-)A_{12}$. Thus the minimal and the maximal ranks of A relative to A_{22} are, in fact, determined by the term $E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}$. It is quite easy to see that

$$(3.3) \quad \min_A r(A) = \min_{A_{22}} r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}] + t,$$

$$(3.4) \quad \max_A r(A) = \max_{A_{22}} r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}] + t.$$

Since $A_{11} = A_{11}^T$, $A_{12} = A_{21}^T$, we have $G_1 = H_1^T$. By $E_{G_1} = I - G_1G_1^+$, $F_{H_1} = I - H_1^+H_1$, it is easy to verify that $E_{G_1}^T = F_{H_1} = E_{G_1}$.

By Lemma 2.2 and $BV_2 = 0$, $A_{11} = A_{11}^T$, we have

$$(3.5) \quad r \begin{pmatrix} A_{11} \\ A_{21} \end{pmatrix} = r(U^T B V_1 \Sigma^{-1}) = r(B V_1) = r(B(V_1, V_2)) = r(BV) = r(B),$$

$$(3.6) \quad r \begin{pmatrix} A_{11} & A_{12} \end{pmatrix} = r \begin{pmatrix} A_{11}^T & A_{12} \end{pmatrix} = r(\Sigma^{-1} V_1^T B^T U) = r(B V_1) \\ = r(B(V_1, V_2)) = r(BV) = r(B),$$

$$(3.7) \quad r(A_{11}) = r(U_1^T B V_1 \Sigma^{-1}) = r(\Sigma U_1^T B V_1) = r(V_1 \Sigma U_1^T B(V_1, V_2)) \\ = r(X^T B V) = r(X^T B).$$

By (3.2), (3.3) and Lemma 1, when $r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}] = 0$, $r(A)$ is minimal. By (3.5), (3.6), (3.7) we know that the minimal rank of symmetric solution for the matrix equation $AX = B$ is

$$(3.8) \quad \tilde{m} = 2r(B) - r(X^T B).$$

If the matrix A_{22} satisfies $r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}] = 0$, we obtain the expression of the symmetric minimal rank solution. Let

$$(3.9) \quad A_{22} = A_{21}A_{11}^+A_{12} + N.$$

where $N \in SR^{(n-k) \times (n-k)}$ satisfies $E_{G_1} N F_{H_1} = 0$. Then the symmetric minimal rank solution of the matrix equation $AX = B$ can be expressed as

$$(3.10) \quad A = BX^+ + (BX^+)^T(I - XX^+) + U_2 A_{22} U_2^T,$$

where A_{22} is as (3.9).

When $r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})F_{H_1}]$ is maximal, we can obtain the expression for the symmetric maximal rank solution of the matrix equation $AX = B$. Since $E_{G_1} = F_{H_1}$, and $r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})E_{G_1}]$ being maximal is equivalent to $r(A)$ being maximal, we have

$$(3.11) \quad \max_{A_{22}} r[E_{G_1}(A_{22} - A_{21}A_{11}^+A_{12})E_{G_1}] = r(E_{G_1}).$$

Since E_{G_1} is an idempotent matrix, by Lemma 2.3, 2.4, 2.5, we have

$$\begin{aligned} r(E_{G_1}) &= \text{trace}(E_{G_1}) = n - k - r(G_1 G_1^+) = n - k - r(G_1) \\ &= n - k - r(A_{21}(I - A_{11}^+ A_{11})) \\ &= n - k - r \begin{pmatrix} A_{11} \\ A_{21} \end{pmatrix} + r(A_{11}) \\ &= n - k - r(B) + r(X^T B) = n - r(X) - r(B) + r(X^T B). \end{aligned}$$

By (3.2), (3.4), (3.5), (3.6), (3.7) and Lemma 2.1, we know the maximal rank of symmetric solution of the matrix equation $AX = B$ is

$$(3.12) \quad \tilde{M} = n + r(B) - r(X).$$

Similar to the discussion of the minimal rank solution, the symmetric maximal rank solution of the matrix equation $AX = B$ can be expressed as

$$(3.13) \quad A = BX^+ + (BX^+)^T(I - XX^+) + U_2 A_{22} U_2^T,$$

where $A_{22} = A_{21} A_{11}^+ A_{12} + N$, the arbitrary matrix $N \in SR^{(n-k) \times (n-k)}$ satisfies $r(E_{G_1} N E_{G_1}) = n + r(X^T B) - r(X) - r(B)$.

Combining the above, we can immediately obtain the following theorem about the general solution to Problem 1.

THEOREM 3.1. *Given $X, B \in R^{n \times m}$, and a positive integer s , consider the singular value decomposition of X in (2.3). Then $AX = B$ has symmetric solution with rank of s if and only if*

$$(3.14) \quad BX^+ X = B, X^T B = B^T X,$$

$$(3.15) \quad 2r(B) - r(X^T B) \leq s \leq n + r(B) - r(X).$$

Moreover, the general solution can be written as

$$(3.16) \quad A = BX^+ + (BX^+)^T(I - XX^+) + U_2 A_{22} U_2^T,$$

where $U_2 \in R^{n \times (n-k)}$, $U_2^T U_2 = I_{n-k}$, $N(X^T) = R(U_2)$, and $A_{22} = A_{21} A_{11}^+ A_{12} + N$, $N \in SR^{(n-k) \times (n-k)}$ satisfies $r(E_{G_1} N E_{G_1}) = s + r(X^T B) - 2r(B)$.

Now we discuss further the expression of the symmetric minimal rank solution of $AX = B$ and the solution set $S_{\tilde{m}}$. From the foregoing analysis, we know that given

$X, B \in R^{n \times m}$, if the singular value decomposition of X is as in (2.3), and $AX = B$ satisfies (2.4), then the minimal rank of symmetric solution is $2r(B) - r(X^T B)$. Also the symmetric minimal rank solution can be expressed as

$$(3.17) \quad A = BX^+ + (BX^+)^T(I - XX^+) + U_2 A_{21} A_{11}^+ A_{12} U_2^T + U_2 N U_2^T,$$

where $N \in SR^{(n-k) \times (n-k)}$ satisfies $E_{G_1} N E_{G_1} = 0$.

Next we will discuss (3.17) further.

Equation (3.1) says $A_{11} = U_1^T B V_1 \Sigma^{-1}$, $A_{12} = \Sigma^{-1} V_1^T B^T U_2$, $A_{21} = U_2^T B V_1 \Sigma^{-1}$. Combining (2.3) and Lemma 2.5, we obtain

$$(3.18) \quad X^+ = V_1 \Sigma^{-1} U_1^T, \quad X X^+ = U_1 U_1^T,$$

that is,

$$X X^+ B X^+ = U_1 U_1^T B V_1 \Sigma^{-1} U_1^T = U_1 A_{11} U_1^T \Rightarrow (X X^+ B X^+)^+ = U_1 A_{11}^+ U_1^T.$$

Thus

$$(3.19) \quad A_{11}^+ = U_1^T (X X^+ B X^+)^+ U_1,$$

hence

$$\begin{aligned} U_2 A_{21} A_{11}^+ A_{12} U_2^T &= U_2 U_2^T B V_1 \Sigma^{-1} U_1^T (X X^+ B X^+)^+ U_1 \Sigma^{-1} V_1^T B^T U_2 U_2^T \\ &= (I - X X^+) B X^+ (X X^+ B X^+)^+ (B X^+)^T (I - X X^+). \end{aligned}$$

Substituting the above formula into (3.17), we obtain that the symmetric minimal rank solution of $AX = B$ can be expressed as

$$(3.20) \quad A = A_0 + U_2 N U_2^T,$$

where $A_0 = BX^+ + (BX^+)^T(I - XX^+) + (I - XX^+)BX^+(XX^+BX^+)^+(BX^+)^T(I - XX^+)$, and $N \in SR^{(n-k) \times (n-k)}$ satisfies $E_{G_1} N E_{G_1} = 0$.

Assume the singular value decomposition of $G_1 = A_{21}(I - A_{11}^+ A_{11})$ is

$$(3.21) \quad G_1 = P \begin{pmatrix} \Gamma & 0 \\ 0 & 0 \end{pmatrix} Q^T = P_1 \Gamma Q_1^T,$$

where

$$P = (P_1, P_2) \in OR^{(n-k) \times (n-k)}, \quad P_1 \in R^{(n-k) \times t}, \quad Q = (Q_1, Q_2) \in OR^{k \times k},$$

$$Q_1 \in R^{k \times t}, \quad t = r(G_1), \quad \Gamma = \text{diag}(\alpha_1, \alpha_2, \dots, \alpha_t), \quad \alpha_1 \geq \dots \geq \alpha_t > 0.$$

Then

$$(3.22) \quad G_1 G_1^+ = P_1 P_1^T, \quad E_{G_1} = I - P_1 P_1^T = P_2 P_2^T.$$

Thus from $E_{G_1} N E_{G_1} = 0$, i.e., $P_2 P_2^T N P_2 P_2^T = 0$, we have

$$(3.23) \quad N = P_1 P_1^T M P_1 P_1^T,$$

where $M \in SR^{(n-k) \times (n-k)}$ is arbitrary.

Substituting (3.23) into (3.20), we can obtain the following theorem.

THEOREM 3.2. *Given $X, B \in R^{n \times m}$, assume the singular value decomposition of X is as in (2.3). If (2.4) is satisfied and the singular value decomposition of G_1 is as in (3.21), then the minimal rank of the symmetric solution of $AX = B$ is $2r(B) - r(X^T B)$, and the expression of the symmetric minimal rank solution is*

$$(3.24) \quad A = A_0 + U_2 P_1 P_1^T M P_1 P_1^T U_2^T,$$

where $A_0 = BX^+ + (BX^+)^T(I - XX^+) + (I - XX^+)BX^+ + (XX^+BX^+)^T(I - XX^+)$, and $M \in SR^{(n-k) \times (n-k)}$ is arbitrary.

4. The expression of the solution to Problem II. From (3.24), it is easy to verify that $S_{\tilde{m}}$ is a closed convex set. Therefore there exists a unique solution \tilde{A} to Problem II. Now we give an expression for \tilde{A} .

The symmetric matrix set $SR^{n \times n}$ is a subspace of $R^{n \times n}$. Let $(SR^{n \times n})^\perp$ be the orthogonal complement space of $SR^{n \times n}$. Then for any $A^* \in R^{n \times n}$, we have

$$(4.1) \quad A^* = A_1^* + A_2^*$$

where $A_1^* \in SR^{n \times n}$, $A_2^* \in (SR^{n \times n})^\perp$. Partition the symmetric matrices

$$U^T A_0 U, \quad U^T A_1^* U$$

as

$$(4.2) \quad U^T A_0 U = \begin{pmatrix} A_{01} & A_{02} \\ A_{03} & A_{04} \end{pmatrix}, \quad U^T A_1^* U = \begin{pmatrix} A_{11}^* & A_{12}^* \\ A_{21}^* & A_{22}^* \end{pmatrix},$$

where $A_{01} \in SR^{k \times k}$ and $A_{11}^* \in SR^{k \times k}$. Then we have the following theorem.

THEOREM 4.1. *Given $X, B \in R^{n \times m}$, assume the singular value decomposition of X is as in (2.3). Assume (2.4) is satisfied, the singular value decomposition of G_1 is as in (3.21) and let $A^* \in R^{n \times n}$ be given. Then Problem II has a unique solution \tilde{A} , which can be written as*

$$(4.3) \quad \tilde{A} = A_0 + U_2 P_1 P_1^T (A_{22}^* - A_{04}) P_1 P_1^T U_2^T,$$

where $A_0 = BX^+ + (BX^+)^T(I - XX^+) + (I - XX^+)BX^+ + (XX^+BX^+)^+ (BX^+)^T(I - XX^+)$, and A_{22}^* , and A_{04} are given by (4.2).

Proof. For any $A^* \in R^{n \times n}$, we have

$$(4.4) \quad A^* = A_1^* + A_2^*,$$

where $A_1^* \in SR^{n \times n}$, $A_2^* \in (SR^{n \times n})^\perp$.

Utilizing the invariance of Frobenius norm for orthogonal matrices, for $A \in S_{\tilde{m}}$, by (3.24), (4.2) and $P_1 P_1^T + P_2 P_2^T = I$, $P_1 P_1^T P_2 P_2^T = 0$, where $P_1 P_1^T$, $P_2 P_2^T$ are orthogonal projection matrices, we obtain

$$(4.5) \quad \|A^* - A\|^2 = \|A_1^* + A_2^* - A\|^2 = \|A_1^* - A\|^2 + \|A_2^*\|^2.$$

Thus $\min_{A \in S_{\tilde{m}}} \|A^* - A\|$ is equivalent to $\min_{A \in S_{\tilde{m}}} \|A_1^* - A\|$. Also

$$\begin{aligned} \|A_1^* - A\|^2 &= \|A_1^* - A_0 - U_2 P_1 P_1^T M P_1 P_1^T U_2^T\|^2 \\ &= \left\| A_1^* - A_0 - U \begin{pmatrix} 0 & 0 \\ 0 & P_1 P_1^T M P_1 P_1^T \end{pmatrix} U^T \right\|^2 \\ &= \left\| U^T A_1^* U - U^T A_0 U - \begin{pmatrix} 0 & 0 \\ 0 & P_1 P_1^T M P_1 P_1^T \end{pmatrix} \right\|^2 \\ &= \left\| \begin{pmatrix} A_{11}^* & A_{12}^* \\ A_{21}^* & A_{22}^* \end{pmatrix} - \begin{pmatrix} A_{01} & A_{02} \\ A_{03} & A_{04} \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & P_1 P_1^T M P_1 P_1^T \end{pmatrix} \right\|^2 \\ &= \|A_{11}^* - A_{01}\|^2 + \|A_{12}^* - A_{02}\|^2 + \|A_{21}^* - A_{03}\|^2 \\ &\quad + \|A_{22}^* - A_{04} - P_1 P_1^T M P_1 P_1^T\|^2 \\ &= \|A_{11}^* - A_{01}\|^2 + \|A_{12}^* - A_{02}\|^2 + \|A_{21}^* - A_{03}\|^2 + \|(A_{22}^* - A_{04})P_2 P_2^T\|^2 \\ &\quad + \|(A_{22}^* - A_{04})P_1 P_1^T - P_1 P_1^T M P_1 P_1^T\|^2 \\ &= \|A_{11}^* - A_{01}\|^2 + \|A_{12}^* - A_{02}\|^2 + \|A_{21}^* - A_{03}\|^2 + \|(A_{22}^* - A_{04})P_2 P_2^T\|^2 \\ &\quad + \|P_2 P_2^T (A_{22}^* - A_{04})P_1 P_1^T\|^2 + \|P_1 P_1^T (A_{22}^* - A_{04})P_1 P_1^T - P_1 P_1^T M P_1 P_1^T\|^2. \end{aligned}$$

Hence $\min_{A \in S_{\bar{m}}} \|A^* - A\|$ is equivalent to

$$(4.6) \quad \min_{M \in SR^{(n-k) \times (n-k)}} \|P_1 P_1^T (A_{22}^* - A_{04}) P_1 P_1^T - P_1 P_1^T M P_1 P_1^T\|.$$

Obviously, the solution of (4.6) can be written as

$$(4.7) \quad M = A_{22}^* - A_{04} + P_2 P_2^T \widetilde{M} P_2 P_2^T, \quad \forall \widetilde{M} \in SR^{(n-k) \times (n-k)}$$

Substituting (4.7) into (3.24), we get that the unique solution to Problem II can be expressed as in (4.3). \square

REFERENCES

- [1] S.K. Mitra. Fixed rank solutions of linear matrix equations. *Sankhya, Ser. A.*, 35:387–392, 1972.
- [2] S.K. Mitra. The matrix equation $AX = C, XB = D$. *Linear Algebra Appl.*, 59:171–181, 1984.
- [3] F. Uhlig. On the matrix equation $AX = B$ with applications to the generators of controllability matrix. *Linear Algebra Appl.*, 85:203–209, 1987.
- [4] S.K. Mitra. A pair of simultaneous linear matrix equations $A_1 X_1 B_1 = C_1, A_2 X_2 B_2 = C_2$ and a matrix programming problem. *Linear Algebra Appl.*, 131:107–123, 1990.
- [5] Y. Tian. The minimal rank of the matrix expression $A - BX - YC$. *Missouri J. Math. Sci.*, 14:40–48, 2002.
- [6] Y. Tian. The maximal and minimal ranks of some expressions of generalized inverses of matrices. *Southeast Asian Bull. Math.*, 25:745–755, 2002.
- [7] S.G. Wang, M.X. Wu, and Z.Z. Jia. *Matrix Inequalities*. Science Press, 2006.
- [8] L. Zhang. A class of inverse eigenvalue problems of symmetric matrices. *Numer. Math. J. Chinese Univ.*, 12(1):65–71, 1990.